

Injektivität \times

$$u = \begin{pmatrix} u_1 \\ u_2 \\ 0 \end{pmatrix} \neq v = \begin{pmatrix} u_1 \\ u_2 \\ 1 \end{pmatrix} \text{ sind}$$

$$\phi(u) = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \phi(v) \quad \checkmark$$

\checkmark

Surjektivität

$$\forall u \in \mathbb{R}^2$$

$$\exists v \in \mathbb{R}^3$$

$$u = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

$$v = \begin{pmatrix} u_1 \\ u_2 \\ 0 \end{pmatrix}$$

$$\phi(v) = u$$

$$\phi(v) = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = u$$

1. Beispiel

4.3.2011

$$\phi: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

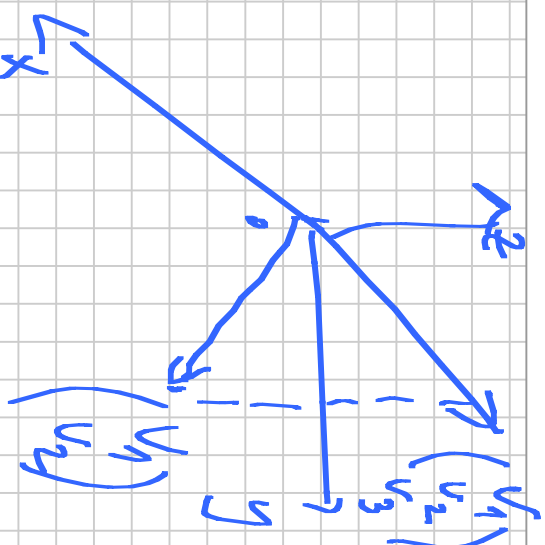
$$\phi \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$$

Linearität

$$1) \quad \phi(u+v) = \phi(u) + \phi(v)$$

 $\forall u, v \in \mathbb{R}^3$

$$\begin{aligned} \phi \begin{pmatrix} u_1 + v_1 \\ u_2 + v_2 \\ u_3 + v_3 \end{pmatrix} &= \begin{pmatrix} u_1 + v_1 \\ u_2 + v_2 \end{pmatrix} + \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \phi \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} + \phi \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \end{aligned}$$



$$2) \quad \phi(\lambda v) = \lambda \phi(v) \quad \forall \lambda \in \mathbb{R} \quad \forall v \in \mathbb{R}^3$$

$$\phi\left(\lambda \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}\right) = \phi\left(\begin{pmatrix} \lambda v_1 \\ \lambda v_2 \\ \lambda v_3 \end{pmatrix}\right) = \begin{pmatrix} \lambda v_1 \\ \lambda v_2 \\ \lambda v_3 \end{pmatrix} = \lambda \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \lambda \phi\left(\begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}\right)$$

Standardbasen:

$$\mathbb{R}^3 \quad \left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}\right), \quad \mathbb{R}^2 \quad \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}\right)$$

$$\phi\left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad \phi\left(\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad \phi\left(\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

